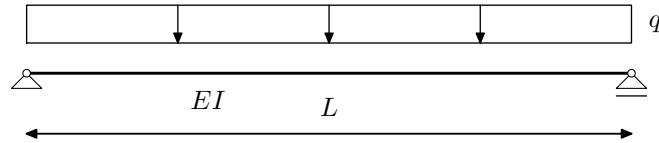


METODA KONAČIH ELEMENATA

Finite Element Method (FEM)

Primjer 1. *Metodom konačnih elemenata odrediti progib $w_{L/2}$ u sredini proste grede raspona L konstantnog poprečnog presjeka I i modula elastičnosti E , opterećene jednoliko distribuiranim opterećenjem q*



Matrica krutosti grednog konačnog elementa (nepoznati pomaci čvorova okomito na os i kutevi zaokreta čvorova, 4 stupnja slobode) duljine L^e glasi

$$\mathbf{k}^e = \begin{bmatrix} \frac{12}{L^3} & -\frac{6}{L^2} & -\frac{12}{L^3} & -\frac{6}{L^2} \\ -\frac{6}{L^2} & \frac{4}{L} & \frac{6}{L^2} & \frac{2}{L} \\ -\frac{12}{L^3} & \frac{6}{L^2} & \frac{12}{L^3} & \frac{6}{L^2} \\ -\frac{6}{L^2} & \frac{2}{L} & \frac{6}{L^2} & \frac{4}{L} \end{bmatrix} . \quad (1.1)$$

Vektor sila upetosti takvog grednog konačnog elementa opterećenog jednoliko distribuiranim opterećenjem glasi

$$\mathbf{q}^e = \begin{bmatrix} \frac{qL^e}{2} \\ -\frac{qL^e{}^2}{12} \\ \frac{qL^e}{2} \\ \frac{qL^e{}^2}{12} \end{bmatrix} . \quad (1.2)$$

Podijelimo područje (gredu) na dva konačna elementa jednake duljine, $L^e = L/2$. Elementarna matrica krutosti svakog konačnog elementa glasi

$$\mathbf{k}^e = \begin{bmatrix} \frac{96}{L^3} & -\frac{24}{L^2} & -\frac{96}{L^3} & -\frac{24}{L^2} \\ -\frac{24}{L^2} & \frac{8}{L} & \frac{24}{L^2} & \frac{4}{L} \\ -\frac{96}{L^3} & \frac{24}{L^2} & \frac{96}{L^3} & \frac{24}{L^2} \\ -\frac{24}{L^2} & \frac{4}{L} & \frac{24}{L^2} & \frac{8}{L} \end{bmatrix} , \quad (1.3)$$

elementarni vektor sila upetosti svakog konačnog elementa glasi

$$\mathbf{q}^e = \begin{bmatrix} \frac{qL}{4} \\ -\frac{qL^2}{48} \\ \frac{qL}{4} \\ \frac{qL^2}{48} \end{bmatrix} . \quad (1.4)$$

Uklapanjem elementarnih matrica krutosti i elementarnih vektora upetosti slijede globalna matrica krutosti

$$\mathbf{K} = \begin{bmatrix} \frac{96}{L^3} & -\frac{24}{L^2} & -\frac{96}{L^3} & -\frac{24}{L^2} & 0 & 0 \\ -\frac{24}{L^2} & \frac{8}{L} & \frac{24}{L^2} & \frac{4}{L} & 0 & 0 \\ -\frac{96}{L^3} & \frac{24}{L^2} & \frac{96}{L^3} + \frac{96}{L^3} & \frac{24}{L^2} - \frac{24}{L^2} & -\frac{96}{L^3} & -\frac{24}{L^2} \\ -\frac{24}{L^2} & \frac{4}{L} & \frac{24}{L^2} - \frac{24}{L^2} & \frac{8}{L} + \frac{8}{L} & \frac{24}{L^2} & \frac{4}{L} \\ 0 & 0 & -\frac{96}{L^3} & \frac{24}{L^2} & \frac{96}{L^3} & \frac{24}{L^2} \\ 0 & 0 & -\frac{24}{L^2} & \frac{4}{L} & \frac{24}{L^2} & \frac{8}{L} \end{bmatrix} = \begin{bmatrix} \frac{96}{L^3} & -\frac{24}{L^2} & -\frac{96}{L^3} & -\frac{24}{L^2} & 0 & 0 \\ -\frac{24}{L^2} & \frac{8}{L} & \frac{24}{L^2} & \frac{4}{L} & 0 & 0 \\ -\frac{96}{L^3} & \frac{24}{L^2} & \frac{192}{L^3} & 0 & -\frac{96}{L^3} & -\frac{24}{L^2} \\ -\frac{24}{L^2} & \frac{4}{L} & 0 & \frac{16}{L} & \frac{24}{L^2} & \frac{4}{L} \\ 0 & 0 & -\frac{96}{L^3} & \frac{24}{L^2} & \frac{96}{L^3} & \frac{24}{L^2} \\ 0 & 0 & -\frac{24}{L^2} & \frac{4}{L} & \frac{24}{L^2} & \frac{8}{L} \end{bmatrix} , \quad (1.5)$$

i globalni vektor sila upetosti

$$\mathbf{q} = \begin{bmatrix} \frac{qL}{4} \\ -\frac{qL^2}{48} \\ \frac{qL}{4} + \frac{qL}{4} \\ \frac{qL^2}{48} - \frac{qL^2}{48} \\ \frac{qL}{4} \\ \frac{qL^2}{48} \end{bmatrix} = \begin{bmatrix} \frac{qL}{4} \\ -\frac{qL^2}{48} \\ \frac{qL}{2} \\ 0 \\ \frac{qL}{4} \\ \frac{qL^2}{48} \end{bmatrix} . \quad (1.6)$$

Dobivamo sustav jednažbi

$$\begin{bmatrix} \frac{96}{L^3} & -\frac{24}{L^2} & -\frac{96}{L^3} & -\frac{24}{L^2} & 0 & 0 \\ -\frac{24}{L^2} & \frac{8}{L} & \frac{24}{L^2} & \frac{4}{L} & 0 & 0 \\ -\frac{96}{L^3} & \frac{24}{L^2} & \frac{192}{L^3} & 0 & -\frac{96}{L^3} & -\frac{24}{L^2} \\ -\frac{24}{L^2} & \frac{4}{L} & 0 & \frac{16}{L} & \frac{24}{L^2} & \frac{4}{L} \\ 0 & 0 & -\frac{96}{L^3} & \frac{24}{L^2} & \frac{96}{L^3} & \frac{24}{L^2} \\ 0 & 0 & -\frac{24}{L^2} & \frac{4}{L} & \frac{24}{L^2} & \frac{8}{L} \end{bmatrix} \begin{bmatrix} w_0 \\ \varphi_0 \\ w_1 \\ \varphi_1 \\ w_2 \\ \varphi_2 \end{bmatrix} = \begin{bmatrix} \frac{qL}{4} \\ -\frac{qL^2}{48} \\ \frac{qL}{2} \\ 0 \\ \frac{qL}{4} \\ \frac{qL^2}{48} \end{bmatrix} . \quad (1.7)$$

Uvrštavanjem rubnih uvjeta, slobodno oslonjeni rubovi $x = 0$ i $x = L$, $w_0 = w_2 = 0$, slijedi manji sustav

$$\begin{bmatrix} \frac{8}{L} & \frac{24}{L^2} & \frac{4}{L} & 0 \\ \frac{24}{L^2} & \frac{192}{L^3} & 0 & -\frac{24}{L^2} \\ \frac{4}{L} & 0 & \frac{16}{L} & \frac{4}{L} \\ 0 & -\frac{24}{L^2} & \frac{4}{L} & \frac{8}{L} \end{bmatrix} \begin{bmatrix} \varphi_0 \\ w_1 \\ \varphi_1 \\ \varphi_2 \end{bmatrix} = \begin{bmatrix} -\frac{qL^2}{48} \\ \frac{qL}{2} \\ 0 \\ \frac{qL^2}{48} \end{bmatrix} . \quad (1.8)$$

Rješenje sustava daje vrijednosti vektora nepoznatih pomaka

$$\begin{bmatrix} \varphi_0 \\ w_1 \\ \varphi_1 \\ \varphi_2 \end{bmatrix} = \begin{bmatrix} -\frac{qL^3}{24EI} \\ \frac{5qL^4}{384EI} \\ 0 \\ \frac{qL^3}{24EI} \end{bmatrix} . \quad (1.9)$$