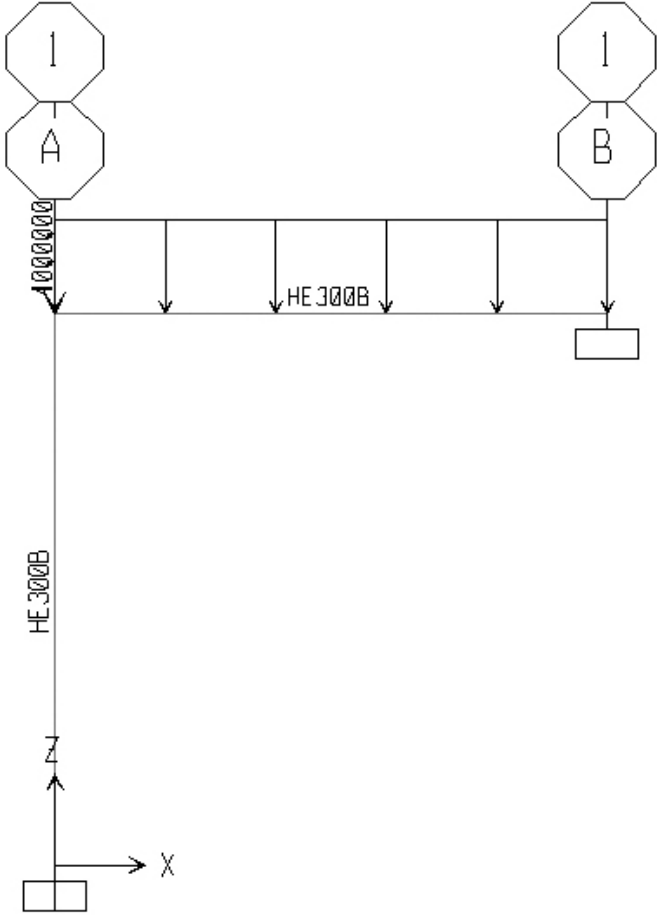
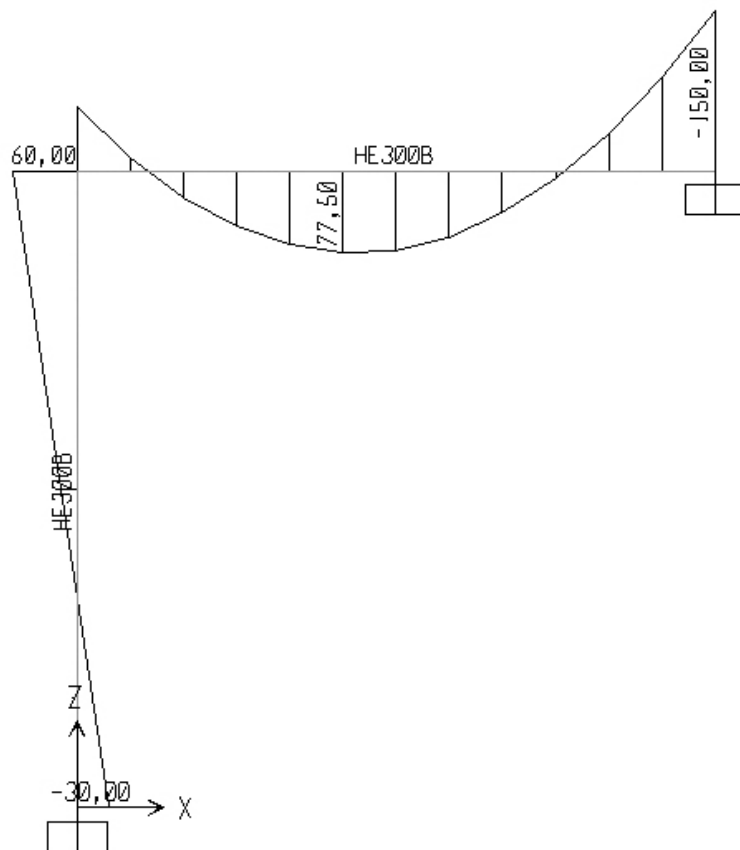


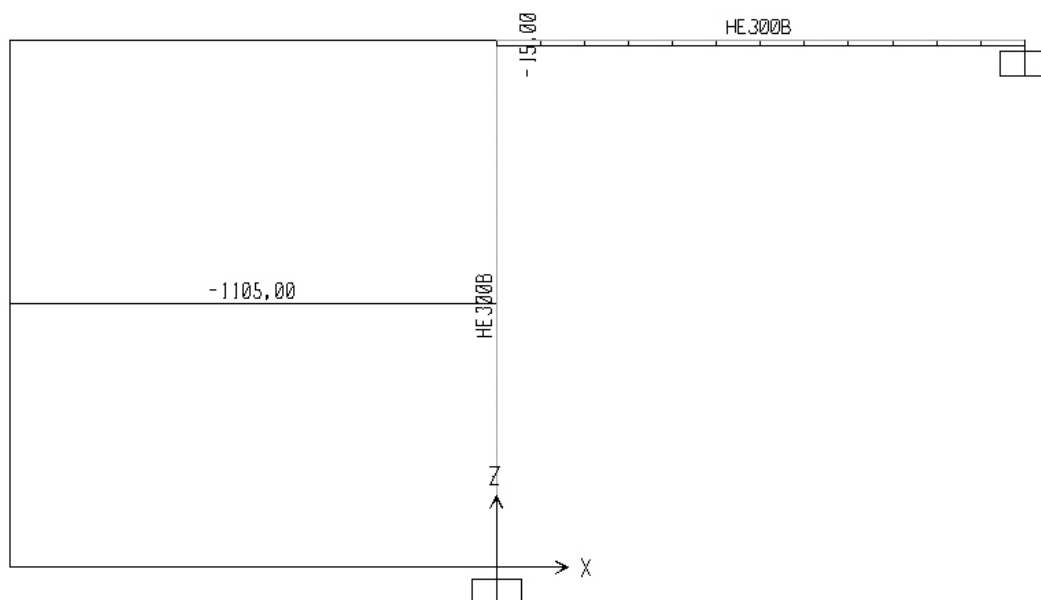
Primjer 7.2.1



Slika 1. : Poluokvir s opterećenjima



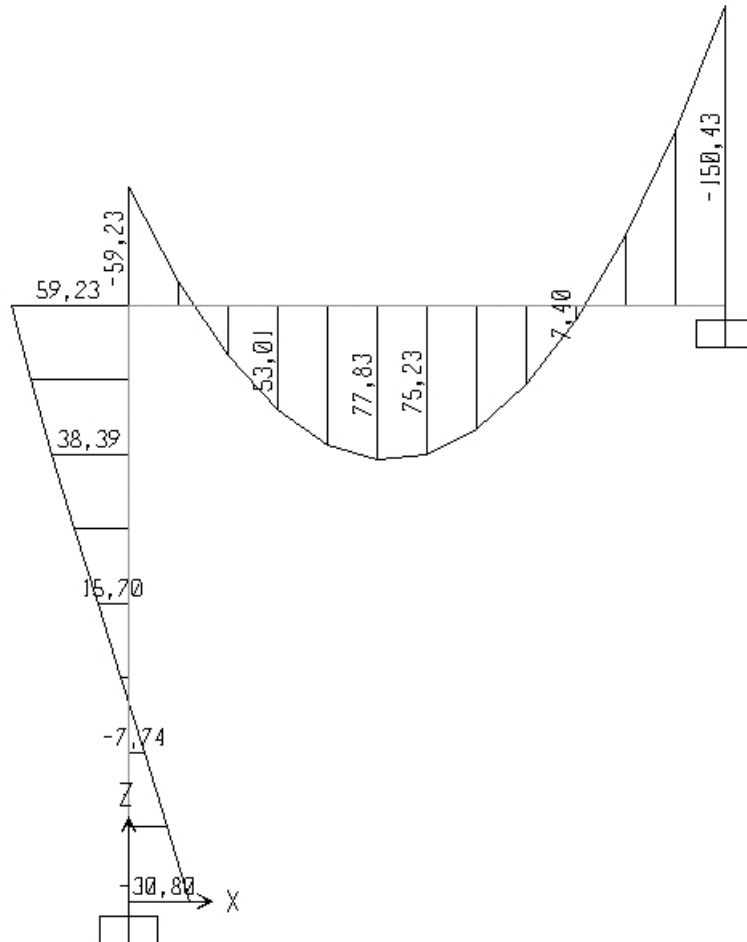
Slika 2. : Momentni dijagram prema linearnom proračunu



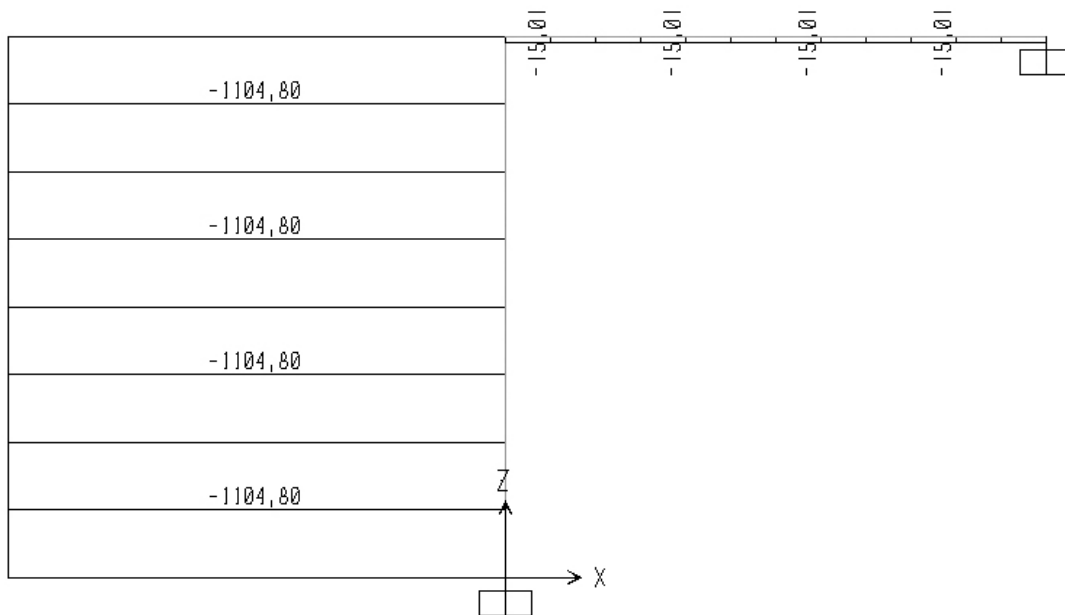
Slika 3. : Dijagram uzdužnih sila prema linearnom proračunu

	Joint Text	OutputCase Text	CaseType Text	StepType Text	U1 m	U2 m	U3 m	R1 Radians	R2 Radians	R3 Radians
▶	2	opterećenje	NonStatic	Max	000000003021	0	-0,0000002224	0	0,001812	0
	2	opterećenje	NonStatic	Min	000000003021	0	-0,0000002224	0	0,001812	0

Slika 4. : Pomaci slobodnog čvora prema nelinearnom proračunu



Slika 5. : Momentni dijagram prema nelinearnom proračunu



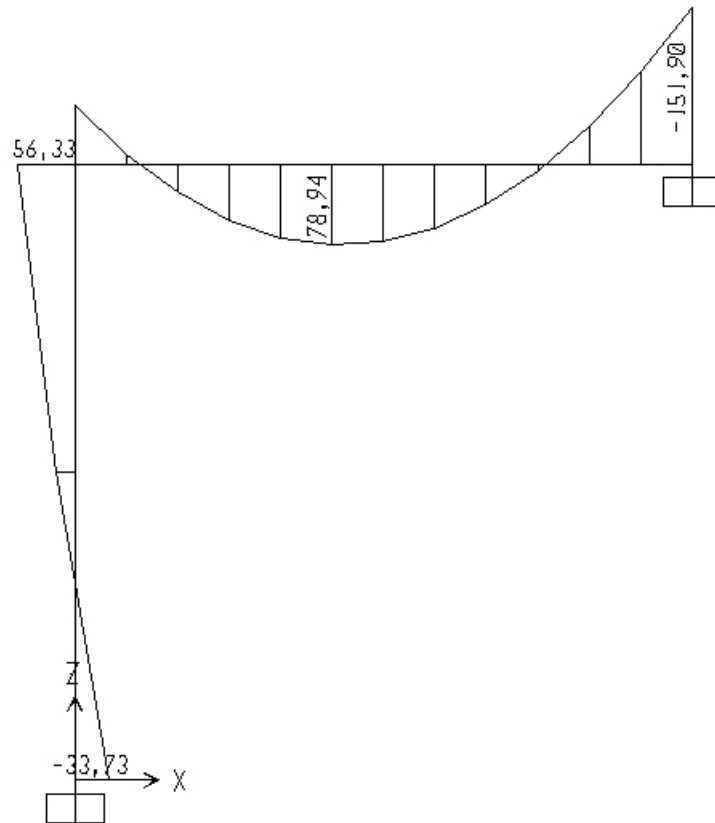
Slika 6. : Dijagram uzdužnih sila prema nelinearnom proračunu

### Primjer 7.2.2

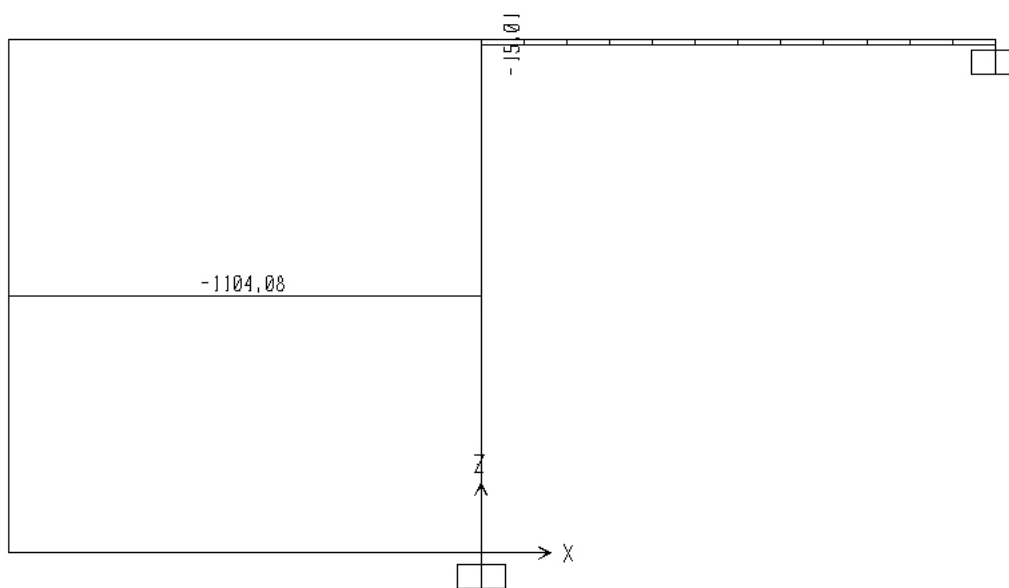
Isti poluokvir kao iz prošlog primjera, ali je  $I = 5696 \text{ cm}^4$ , HE 200B.

	Joint Text	OutputCase Text	CaseType Text	StepType Text	U1 m	U2 m	U3 m	R1 Radians	R2 Radians	R3 Radians
▶	2	opterećenje	NonStatic	Max	000000005767	0	-0,0000004241	0	0,008393	0
	2	opterećenje	NonStatic	Min	000000005767	0	-0,0000004241	0	0,008393	0

Slika 7. : Pomaci slobodnog čvora prema nelinearnom proračunu

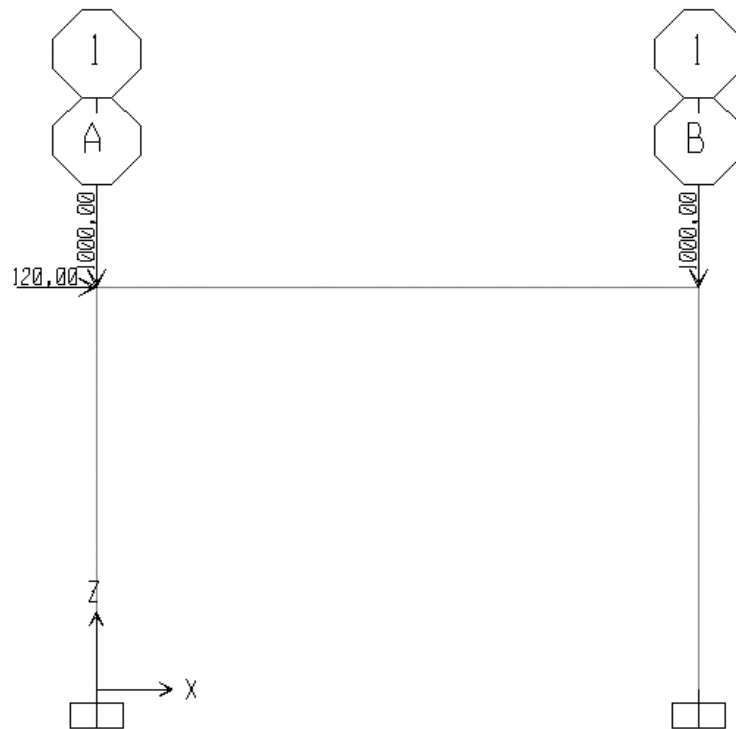


Slika 8. : Momentni dijagram prema nelinearnom proračunu

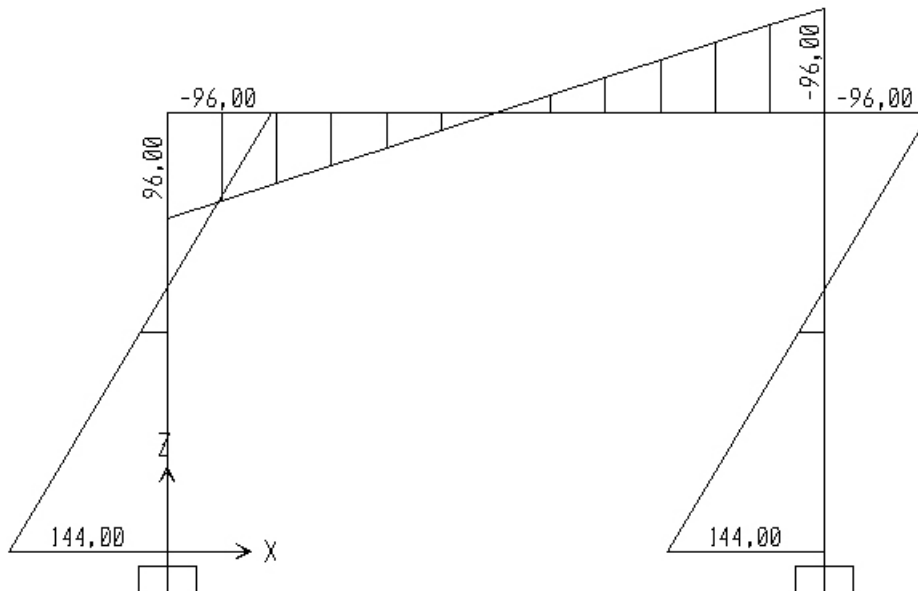


Slika 9. : Dijagram uzdužnih sila prema nelinearnom proračunu

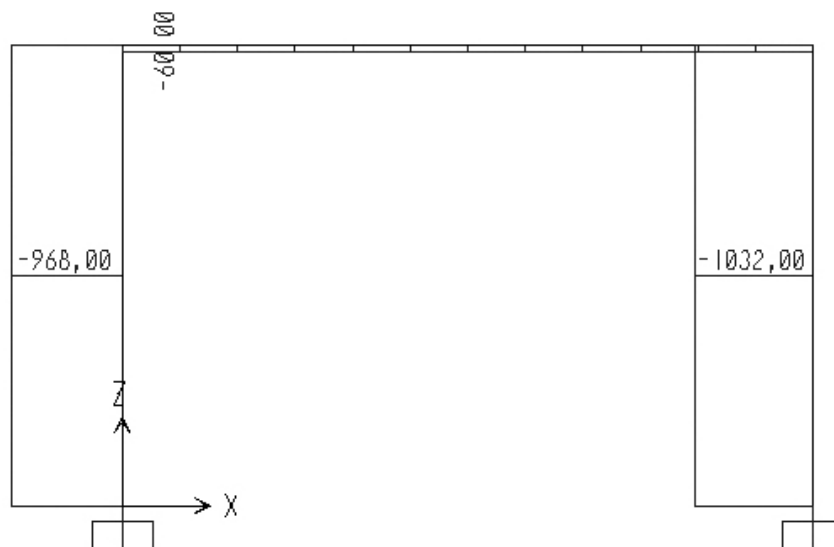
### Primjer 7.2.3



Slika 10. : Okvir s opterećenjima, profil HE 300B



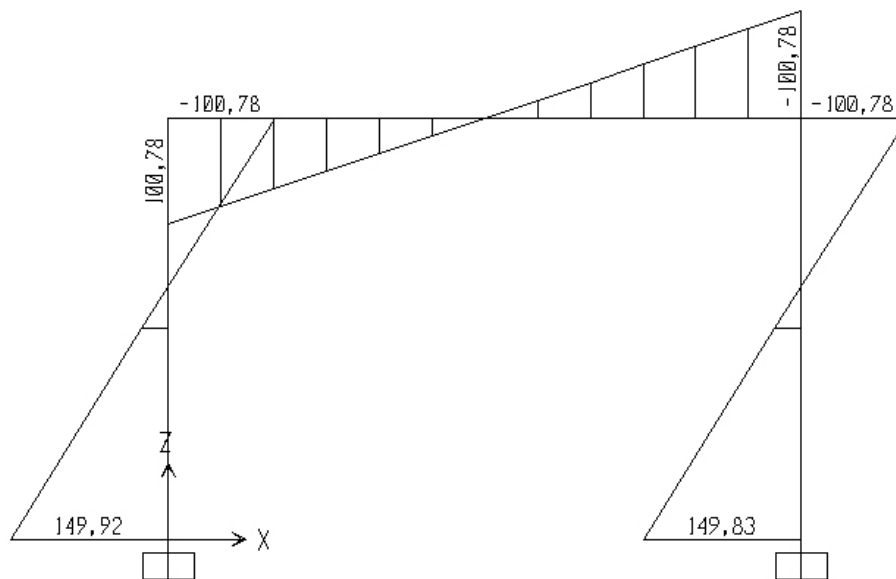
Slika 11. : Momentni dijagram prema linearnom proračunu



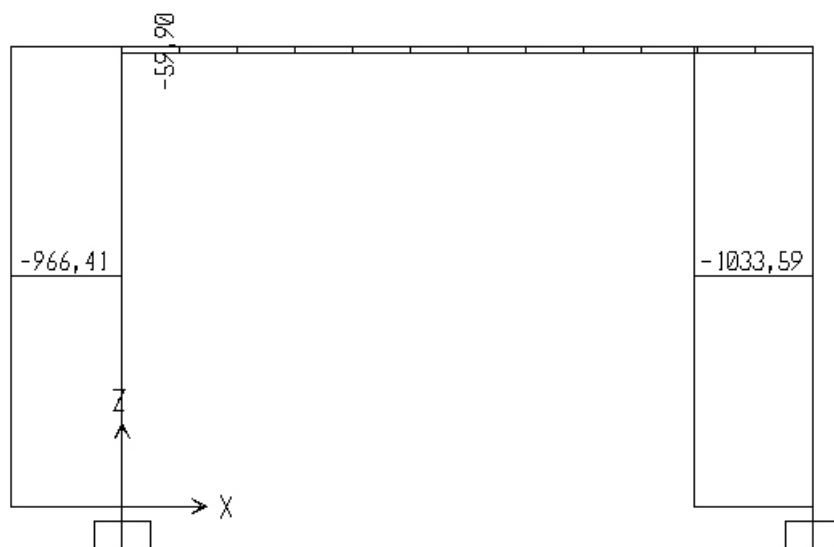
Slika 12. : Dijagram uzdužnih sila prema linearnom proračunu

	Joint Text	Output Case Text	Case Type Text	Step Type Text	U1 m	U2 m	U3 m	R1 Radians	R2 Radians	R3 Radians
▶	2	opterećenje	NonStatic	Max	0,010681	0	-0,0000001297	0	0,002003	0
	2	opterećenje	NonStatic	Min	0,010681	0	-0,0000001297	0	0,002003	0
	3	opterećenje	NonStatic	Max	0,010681	0	-0,0000001387	0	0,002003	0
	3	opterećenje	NonStatic	Min	0,010681	0	-0,0000001387	0	0,002003	0

Slika 13. : Pomaci slobodnih čvorova prema nelinearnom proračunu



Slika 14. : Momentni dijagram prema nelinearnom proračunu

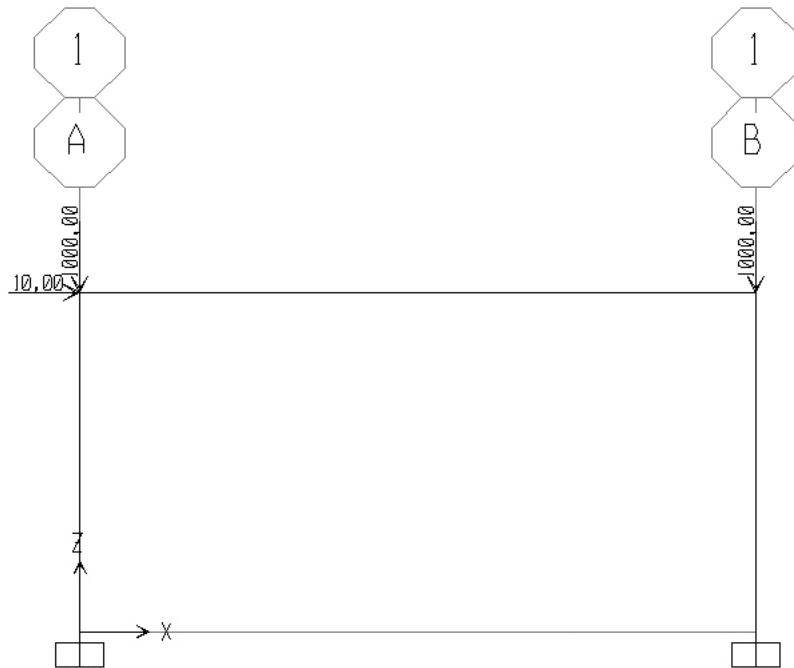


Slika 15. : Dijagram uzdužnih sila prema nelinearnom proračunu

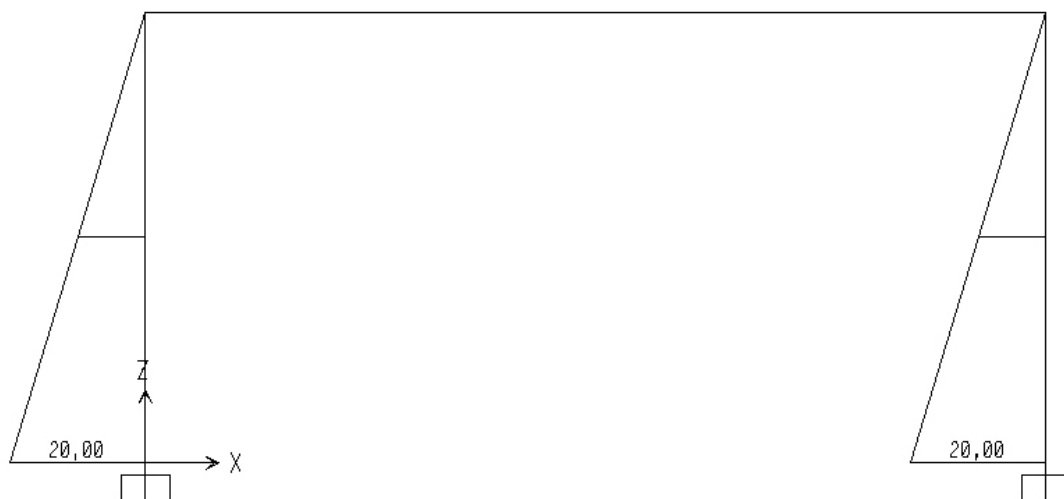


### Primjer 7.2.4

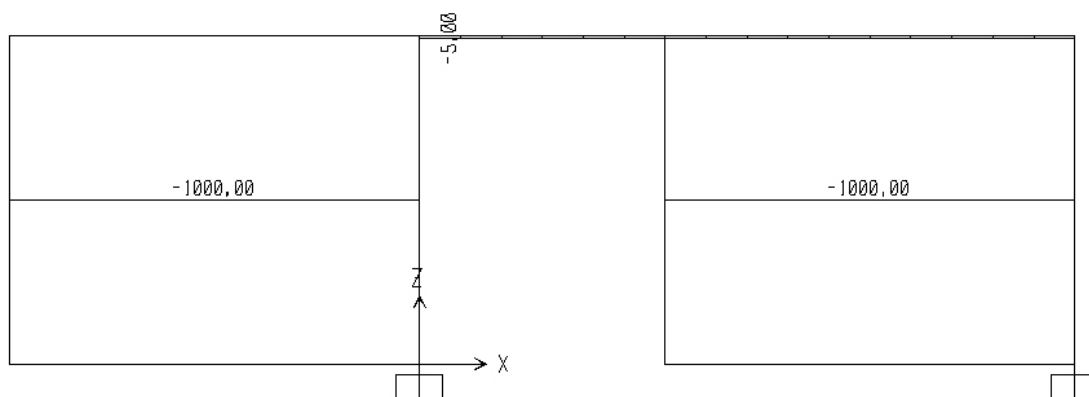
Okvir iz Primjera 7.2.3, profil HE 200B. Zglobovi na vrhu stupova.



Slika 16. Okvir s opterećenjima



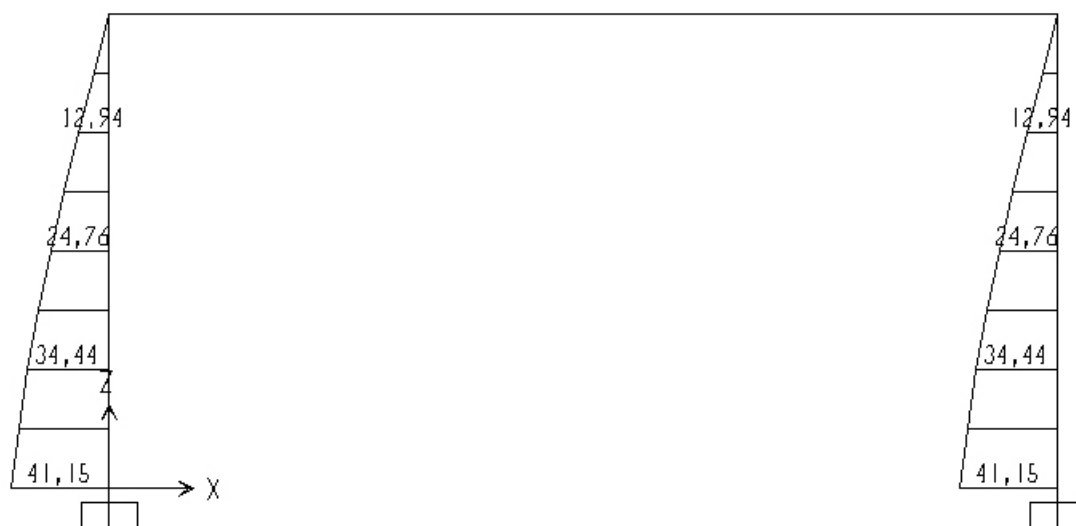
Slika 17. : Momentni dijagram prema linearnom proračunu



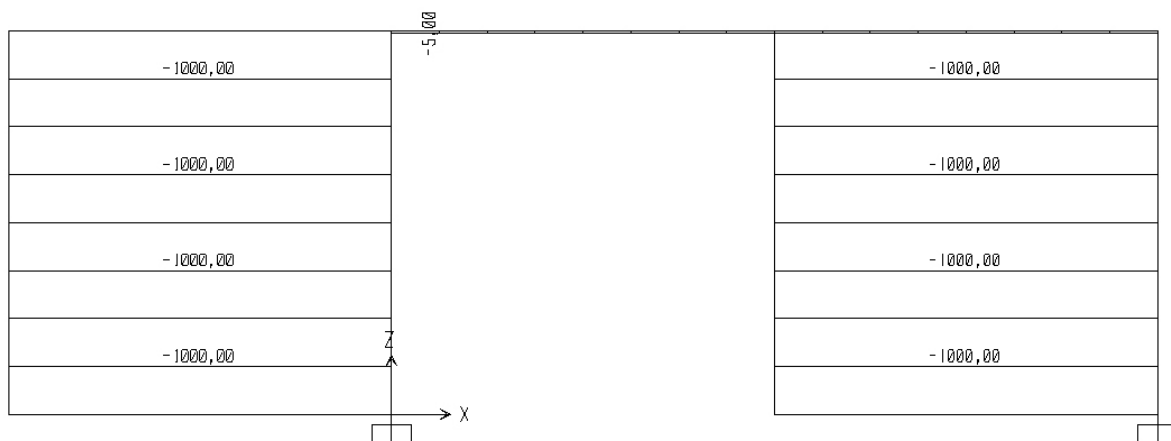
Slika 18. : Dijagram uzdužnih sila prema linearnom proračunu

	Joint Text	OutputCase Text	CaseType Text	StepType Text	U1 m	U2 m	U3 m	R1 Radians	R2 Radians	R3 Radians
▶	2	opterećenje	NonStatic	Max	0,021328	0	-0,0000002561	0	-0,00234	0
	2	opterećenje	NonStatic	Min	0,021328	0	-0,0000002561	0	-0,00234	0
	3	opterećenje	NonStatic	Max	0,021328	0	-0,0000002561	0	-0,003526	0
	3	opterećenje	NonStatic	Min	0,021328	0	-0,0000002561	0	-0,003526	0

Slika 19. : Pomaci slobodnih čvorova prema nelinearnom proračunu



Slika 20. : Momentni dijagram prema nelinearnom proračunu



Slika 21. : Dijagram uzdužnih sila prema nelinearnom proračunu