# PRIMJER 1 S.S. - SAP2000

### MJERNE JEDINICE - [kNm]

#### FILE – NEW MODEL – BLANK

#### **DEFINE – SECTION PROPERTIES – LINK/SUPPORT PROPERTIES ADD NEW PROPERTIES**

Definirati element veze (link) sa karakteristikama linearnog dampera Aktivirati stupanj slobode U1 (ostalo su slobodni)

#### MODIFY/SHOW FOR U1

Upisati linearnu krutost (k = 1,0 kN/m) i prigušenje (c = 0)

Link/Support Properties	Link/Support Property Data
Properties       Click to:         Add New Property         Modify/Show Property         Delete Property	Link/Support Type       Damper         Property Name       LIN1         Property Notes       Modify/Show
OK Cancel	Mass     0     Rotational Inettia 1     0       Weight     0     Rotational Inettia 2     0       Rotational Inettia 3     0
Link/Support Directional Properties	Factors For Line, Area and Solid Springs       Property is Defined for This Length In a Line Spring       Property is Defined for This Area In Area and Solid Springs
Direction U1 Type Damper	Directional Properties Direction Fixed NonLinear Properties U1 Modify/Show for U1
Properties Used For All Analysis Cases Effective Stiffness	Modify/Show for U2       U3       R1       Modify/Show for B1
	H2     I     Modify/Show for R2     UK       R3     I     Modify/Show for R3     Cancel       Fix All     Clear All     I
Cancel	

### VIEW – SET 2D VIEW – X-Z PLANE (Y=0) VIEW – SHOW AXES

- Isključiti jedan prozor
- Prikaz u x-z ravnini (model samo u jednoj dimenziji!)
- Isključiti koordinatne osi
- Uključiti vidljivost točaka
- Uključiti oznake točaka i linkova
- Uključiti lokalne osi točaka i linka

#### **DRAW – DRAW TWO JOINT LINK**

- Nacrtati bilo gdje link i promijeniti koordinate točaka na 0,0 i 0,1 (desni klik mišem)
- Duljina linka je 1,0 m u smjeru osi z

**OPTIONS – DIMENSIONS – MINIMUM GRAPHICS FONT SIZE - 8** 

#### Pridružiti masu točki (materijalna točka) Označiti gornju točku linka ASSIGN – JOINT – MASSES

Pridružiti masu kao težinu (mjerna jedinica kN), w = 1,0 kN (m = 100 kg) Masa pridružena u smjeru lokalne osi 3 (globalna os z) – prikazati lokalne osi linka

Specify Joint Mass	
C As Mass	
<ul> <li>As Weight</li> </ul>	
C As Volume and Material Property	
Material +	
Mass Direction	
Coordinate System Joint Loc	al 💌
Weight	
Local 1 Axis Direction	0,
Local 2 Axis Direction	0,
Local 3 Axis Direction	1
Weight Moment of Inertia	
Rotation About Local 1 Axis	0,
Rotation About Local 2 Axis	0,
Rotation About Local 3 Axis	0,
Options	Units
O Add to Existing Masses	KN, m, C 💌
Replace Existing Masses	
C Delete Existing Masses	
ΠΚ	Cancel

Definirati rubne uvjete Označiti donju točku linka ASSIGN – JOINT – RESTRAINTS – upeti spoj Aktivirati samo stupanj slobode u smjeru z (problem s 1 stupnjem slobode - translacija) ANALYZE – SET ANALYSIS OPTIONS – uz

ANALYZE – SET ANALYSIS OPTIONS – SOLVER OPTIONS – standard solver

nalysis Options			
Available DOFs			
Fast DOFs Space Frame Plane Frame Plane Grid Space Truss	<u> </u>	Equation Solver Options	
XZ Plane XY Plane	Cancel Solver Options	Solver Options Standard Solver Advanced Solver Multi-threaded Solver	Analysis Process Options Auto GUI Process C Separate Process
Tabular File     Automatically save Microsoft Access or Excel tabular file after and     File name	alysis	Other Options Always Run Analysis as 32-1 Select Analysis Case for Mass an Analysis Case Name	bit, Even on 64-bit Machines nd Stiffness Text File Output
Uatabase Lables Named Set Liroup	<b>_</b>	ОК	Cancel

Definirati jedinično opterećenje **DEFINE – LOAD PATTERNS – sila (LIVE)** Izbrisati DEAD load

Označiti slobodnu točku linka (točka u kojoj je masa) ASSIGN – LOAD LOADS – FORCES – smjer z (1,0 kN)

Load Pattern Name		Units
+ SILA	-	KN, m, C 💌
Loads		Coordinate System
Force Global X	0,	GLOBAL
Force Global Y	0,	
Force Global Z	1	Options
Moment about Global $ imes$	0,	Replace Existing Loads
Moment about Global Y	0,	C Delete Existing Loads
Moment about Global Z	0,	OK Cancel

## Definirati vremenski promjenljivo opterećenje DEFINE – FUNCTIONS – TIME HISTORY – Add new function (USER)



### Definirati dinamički slučaj opterećenja DEFINE – LOAD CASES – Add new Load Case

Load Case Name Notes	Load Case Type	
KONSTANTA Set Def Name Modify/Show	Time History   Design	
Stiffness to Use Time History Type		
<ul> <li>Zero Initial Conditions - Unstressed State</li> <li>Linear</li> <li>Modal</li> </ul>		
C Stiffness at End of Nonlinear Case C Nonlinear C Direct Integrati		
Important Note: Loads from the Nonlinear Case are NOT included		
	<ul> <li>Transient</li> </ul>	
Modal Load Case	C Periodic	
Use Modes from Lase		
Show Advanced Load Parameters	Modify Delete	
Show Advanced Load Parameters  Time Step Data	Modify Delete	
Show Advanced Load Parameters       Time Step Data       Number of Output Time Steps	Modify Delete	
Show Advanced Load Parameters       Time Step Data       Number of Output Time Steps       Output Time Step Size	Modify Delete	
Show Advanced Load Parameters  Time Step Data Number of Output Time Steps Output Time Step Size  Other Parameters	Modify Delete	
Show Advanced Load Parameters       Time Step Data       Number of Output Time Steps       Output Time Step Size       Other Parameters       Damping	Modify Delete	

### PRIKAZATI OBLIK OSCILIRANJA I PRVI PERIOD (1 S.S.)

Prikazati pomak slobodne točke u vremenu (odgovor stupnja slobode) Označiti točku

### **DISPLAY – SHOW PLOT FUNCTIONS**

Define plot functions – označiti "Joint 2" – Modify Nazvati funkciju "Pomak tocke" i definirati pomak u smjeru osi z

Definirati funkciju brzine i ubrzanja iste točke "Joint 2" (provjeriti broj čvora) Definirati funkciju sile u linku (uzdužna sila)

Plot Functions	Plot Function Trace Display Definition
Plot Functions Choose Function Type to Add Joint2 Click to:	Load Case (Multi-stepped Cases) KONSTANTA
Add Plot Function Add Plot Function Modify/Show Plot Functions Delete Plot Function OK Cancel	Choose Plot Functions       Time Bange         Define Plot Functions       From       0,         List of Functions       Vertical Functions       To       0,         Joint2       Add ->       Add ->       Add ->       Min       Max         K-Remove       Show       Show       Image: Construction of the second seco
Joint Plot Function Plot Function Name Pomak tocke	Axis Labels Horizontal
Joint ID 2	C Solid Line C Dashed Line C Dotted Line
Vector Type Displ     C Abs Displ     C Include all     C Vel     C Abs Vel     C Include one     C Accel     C Abs Accel	Vertical Scale Factor     Save Named Set     Display       Line Color     Show Named Set     Done
Component Cux C RX C UX C RX C UY C RY C UZ C RZ Cancel	

#### PRIKAZATI ANIMACIJU SA DIJAGRAMOM pomak – vrijeme brzina – pomak

sila – vrijeme sila - pomak



-2,40 -1,60 -0,80 0,00 0,80 1,60 2,40 3,20 4,00 4,80

(4,34,2,24)

0K

0,25 0,00



# Dodati prigušenje linearno linku

Link/Support Directional Properties		
_ Identification		
Property Name	damper	
Direction	U1	
Туре	Damper	
NonLinear	No	
Properties Used For All Analysis Cases		
Effective Stiffness	1,	
Effective Damping	0,0316	
OK	Cancel	



